



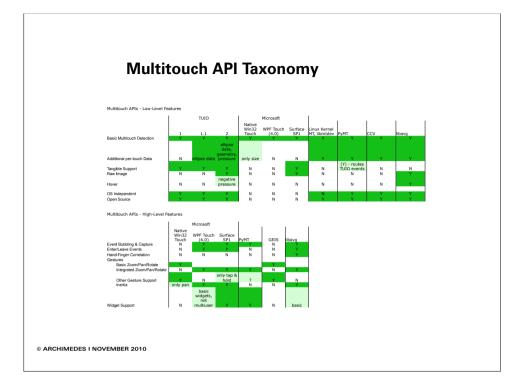
# SOFTWARE DEVELOPMENT FOR TABLETOPS

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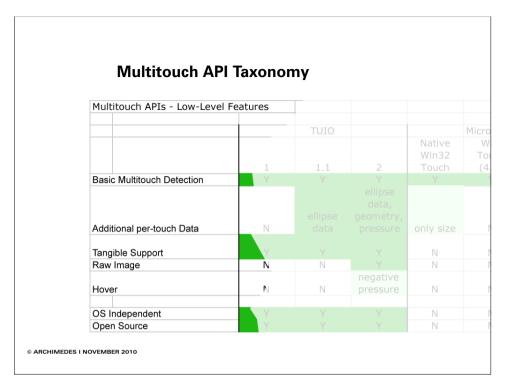
#### **AGENDA**

- Multitouch APIs: Taxonomy of Features
- · Overview of Some Current Multitouch APIs
- · Interlude: Introduction to libavg
- Library Implementation
- · Application-level Considerations

- Taxonomy: Classification of what the APIs provide
- Current APIs: Taxonomy gives us a tool for the evaluation. Too many APIs to evaluate all!
- libavg Intro: Perspective for the following parts we implemented everything from scratch
- Library Implementation: Most of the time for the tutorial
- App-Level Considerations: Typical app lifecycle walkthrough



- -Too much for one slide.
- -Things are in flux. New APIs are appearing etc.
- -Distinction between Low- and High-Level features.
- -From Bottom to Top:
  - Closer -> further away from HW
  - Older -> newer developments
  - Clearer -> less clear requirements



-HW dependence: Wigdor's HW Taxonomy at last year's tutorial

# **Multitouch API Taxonomy**

Multitouch APIs - High-Level Fe	eatures				
		Microsoft			
	Native	WPF			
	Win32	Touch	Surface		
	Touch	(4.0)	SP1	PyMT	GEI
Event Bubbling & Capture	N				N
Enter/Leave Events	N			N	N
Hand-Finger Correlation	N	N	N	N	N
Gestures					
Basic Zoom/Pan/Rotate	Y				
Integrated Zoom/Pan/Rotate	N				N
			only tap &		
Other Gesture Support	Y	N	hold	?	
Inertia	only pan			N	N
		basic			
		widgets,			
		not			
Widget Support	N	multiuser			N

# **Current Multitouch APIs**

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- -Can't evaluate all APIs too many available
- -Selection: Industry standards + interesting developments

# **Current Multitouch APIs: TUIO**

		TUIO	
	1	1.1	2
Basic Multitouch Detection	Υ	Υ	Υ
		allinga	ellipse data,
l		ellipse	geometry,
Additional per-touch Data	N	data	pressure
Tangible Support	Υ	Υ	Υ
Raw Image	N	N	Υ
Hover	N	N	negative pressure
Hover OS Independent	N Y	N	

- -De-Facto industry standard.
- -Network protocol, not library
- -Originally for the reactable (Martin Kaltenbrunner, Ross Bencina et. al.), main feature was marker tracking.
- -Based on OSC
- -1.0: Basic touch data. Supported by/Wrappers exist for virtually all MT devices and tracking libraries.
- -1.1: Reference implementation exists, but little library support. Adds ellipse data
- -2.0: Looks very nice, but no implementation yet.

# **Current Multitouch APIs: TUIO**

#### Some implementations

- iPhone
- Win7 Touch Wrapper
- CCV
- ...

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# **Current Multitouch APIs: Microsoft**

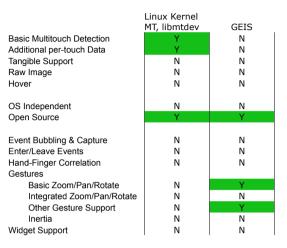
	Microsoft Native Win32 WPF Touch		
	Touch	(4.0)	Surface SP1
Basic Multitouch Detection	Y	Y	Y
Additional per-touch Data	N	N	N
Tangible Support	N	N	Υ
Raw Image	N	N	Υ
Hover	N	N	N
OS Independent	N	N	N
Open Source	N	N	N
Event Bubbling & Capture	N	Y	Υ
Enter/Leave Events	N	Υ	Υ
Hand-Finger Correlation Gestures	N	N	N
Gestures  Basic Zoom/Pan/Rotate	Y	ı	
Integrated Zoom/Pan/Rotate	N	Υ	Υ
Other Gesture Support	Y	N	only tap & hold
Inertia	only pan	Υ	Υ
Widget Support	N	basic widgets, not multiuser	Y
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- Native Win32: WM\_TOUCH, WM\_GESTURE.
  - Missing a good event model no bubbling.
  - WM\_GESTURE separates zoom, pan, rotate.

#### - WPF Touch:

- Integrated into WPF event model
- Very nice manipulation API (zoom/pan/rotate)
- Single-user: Only one control can have focus
- -Surface SP1: Similar features to WPF touch, adds multi-user widgets. Widgets are available for use with WPF touch, so usable with any HW.

#### **Current Multitouch APIs: Linux**



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#### - Kernel MT support:

- Driver-level API (files + ioctls),
- not easy to use,
- ID tracking not guaranteed
- not meant for direct use by applications.

#### -Libmtdev:

- Layer above Kernel MT
- Adds ID tracking
- A little easier to use: function calls instead of ioctls.

#### -Xinput 2.1 extension:

- Work in progress: 2 specs, 1 implementation

-GEIS: Gesture recognition framework. Heart of publicised Ubuntu 10.10 MT support.

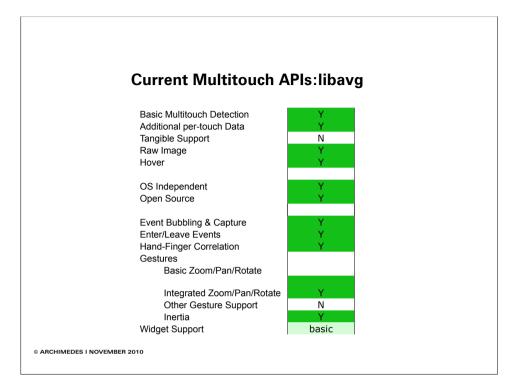
# **Current Multitouch APIs: PyMT**

Basic Multitouch Detection Additional per-touch Data Tangible Support Raw Image Hover	Y Y Y N
OS Independent Open Source	Y Y
Event Bubbling & Capture Enter/Leave Events Hand-Finger Correlation Gestures Basic Zoom/Pan/Rotate	Y N N
Integrated Zoom/Pan/Rotate Other Gesture Support Inertia Widget Support	Y ? N Y

- -Python-based library
- -Mostly implemented in python
- -Interfaces to several low-level libraries.
- -Large widget library couldn't test the quality of the widgets.

# Current Multitouch APIs: CCV Basic Multitouch Detection Additional per-touch Data Tangible Support Raw Image Hover OS Independent Open Source PARCHIMEDES I NOVEMBER 2010

- -One of many tracking libraries that deliver TUIO 1.0 events, but:
- -Mature & well maintained
- -Nice configuration interface
- -Large user base (NUIGroup)



- -Framework with a Python API
- -Lots of green ©

"high-level development plattform for media-centric applications"

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# libavg

"high-level development plattform for media-centric applications"

• Screen layout (xml) + interaction (python)

High-level development plattform for media-centric applications

- Screen layout (xml) + interaction (python)
- 2D Scenegraph

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-Like a 3D engine, just for two dimensions.

# libavg

- Open Source, LGPL License
- Runs on Mac, Linux, Windows
- · Started in 2003
- Since 2007: Development sponsored by Archimedes

- LGPL: Usable for commercial applications. If you add things to the core library, please publish the changes.
- Development at Archimedes: Currently 10 developers across all plattforms
- Currently in the process of delivering a museum with > 70 different exhibits running libavg, including:
  - eye tracking
  - multi-projector blending on curved surfaces
  - Robot terrarium: Real robots, virtual obstacles
  - Of course: Multitouch tables

Code Examples

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- -Show twovideos.py, start it
- -Show videochooser.py, start it

# libavg

Layout elements (nodes):

- Images
- Text
- Videos
- Camera Images
- Vector Graphics
- Plugins

# Layout engine:

- Structure through <div> nodes
- Pos, scale, rotate nodes
- Transparency
- Mask images
- Cropping
- Offscreen buffers (FBO)

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# libavg

# Implementation:

- C++
- OpenGL backend
- Uses:
  - ffmpeg
  - Pango
  - GraphicsMagick
  - libSDL
  - ..

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-All compositing is done on the graphics card

#### Text formatting:

- Paragraph-level layout (like <span>)
- Full utf8 support: Japanese, Chinese, Arabic, Latin (etc) scripts.

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-Utf8: Japanese version of Biodiversity Session Desk: Japanese, Chinese, Latin in one paragraph

# libavg

#### Videos:

- Alpha channel support
- Smaller videos (100x100 pixels incl. alpha): 200 at 30 Hz on a Core i7.
- · Latency-free seeking
- Fast: Shaders, multithreading, sse2 intrinsics...

- -Alpha channel: No performance penalty
- -Seek: single-threaded mode that decodes everything synchronously. Can seek at 30 Hz in 720p videos
- -Rotating earth in biodiversity: Video seeking

# libavg Videos: Sample code

-~/devel/tmp/alphavideos/alphavideos.py

# libavg

#### Plugins:

- New node types
- Extend any other part of libavg
- Written in C++

- -New Node types: 3D rendering (OpenSceneGraph)
- -Custom Windchannel rendering for Computer Sport
- -Other plugins: fiducial tracking, eye tracker

Multitouch driver model:

- TUIO
- Apple Trackpads
- Our own tracker
- (Half-finished linux mtdev driver)

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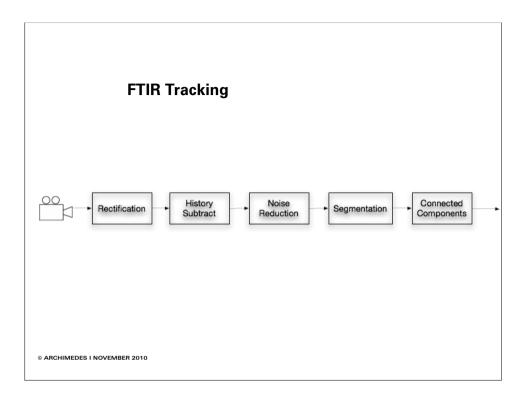
# libavg Ecosystem

- HTW Berlin
- Saar University
- XIBO
- c-base

- -Where else is libavg being used?
- -HTW Berlin: Snatch'em
- -Saar University: Just did a Seminar/student project
- -XIBO: Open Source Digital Signage (web browser plugin)
- -c-base: Hackerspace in Berlin,
  - Original multitouch garage project
  - Several libavg installations
  - Multitouch hackfest last december

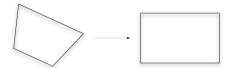
# Library Implementation Output Outpu

- -Go through all the api features and see how they work internally
- -Tip if you don't want to do everything by hand: Use OpenCV.



- -FTIR explained in Florian's tutorial.
- -Standard tracking alg., basic CV.

# FTIR Tracking: Rectification



#### Intrinsic Parameters:

• Barrel/pincushion distortion

#### **Extrinsic Parameters:**

• 3D perspective transform

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Rectification: Turning the camera image into a rectangle ©.

# FTIR Tracking: Rectification

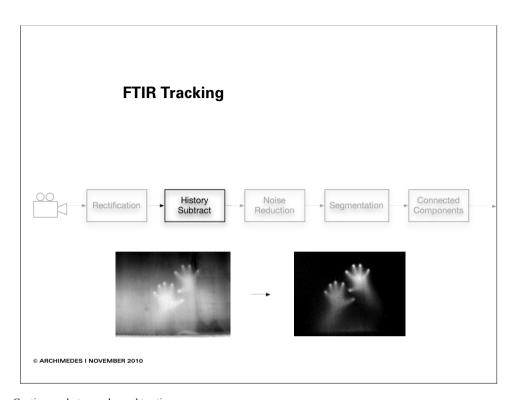
#### Calibration:

- 1. User touches lots of points with known positions.
- 2. Solve overdetermined system with camera params as unknowns.

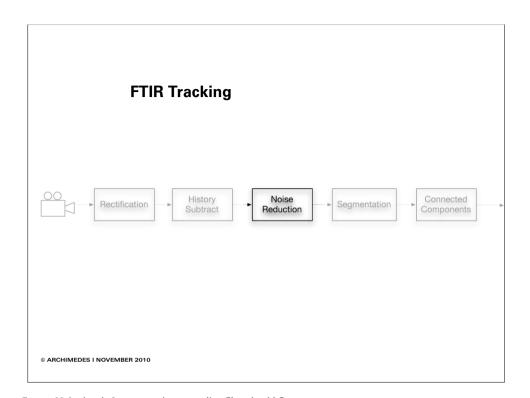
Safer convergence: Solve for intrinsic params first, then for extrinsic params.

[Tsai 87, "A Versatile Camera Calibration Technique...."]

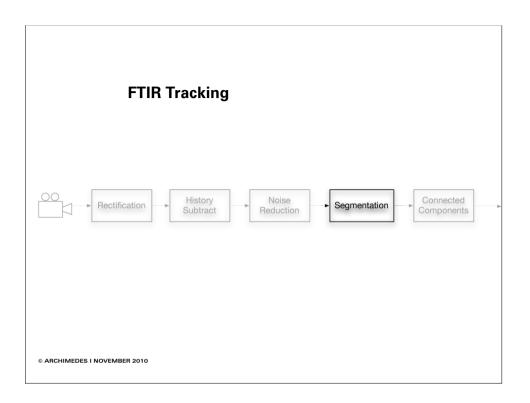
- -Overdetermined system: Least squares.
- -Intrinsic first: Unknowns are

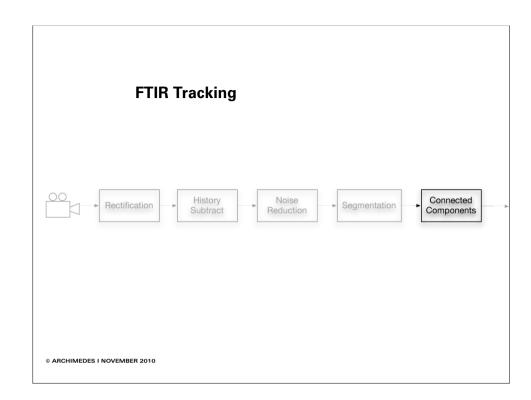


- -Continuous, but very slow subtraction.
- -Initial history: Not just one frame



- -Camera Noise is salt & pepper noise, so median filter should fit.
- -But: Too aggressive in our case. Very small gauss blur helped.





# FTIR Tracking

#### Segmentation:

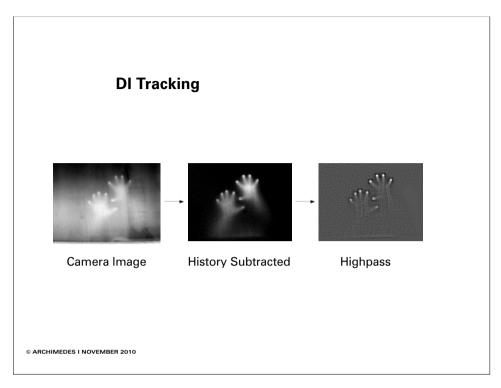
```
for each line:
    find all runs of pixels > threshold
    for each run:
        if underneath run in prev line:
            append to blob
        if underneath more runs:
                  join blobs
        else:
            create new blob
```

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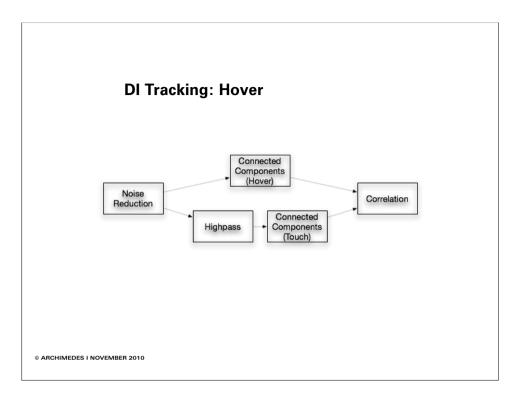
# **DI Tracking**



- -Bad camera images!
- -Bright points where fingers aren't touching, so threshold isn't enough.
- -Solution: Highpass filter

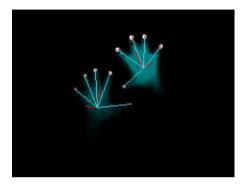


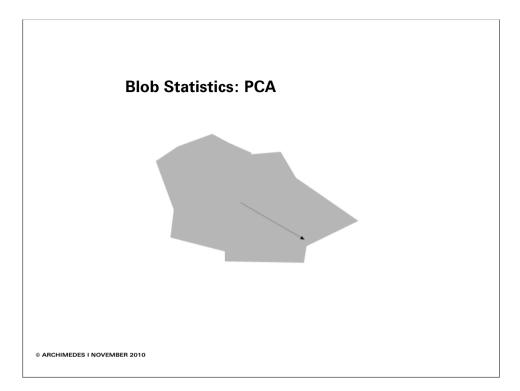
- -Bad camera images!
- -Bright points where fingers aren't touching, so threshold isn't enough.
- -But: the diffuser (aka projection surface) distributes light evenly, so only objects that are touching the surface are in focus.
- -So use highpass filter (image minus gauss blur of image)
- -Or edge detection filters
- -Archimedes Session Desk: Tempered glass, 6mm between ,touch' and surface, wide highpass -> GPU



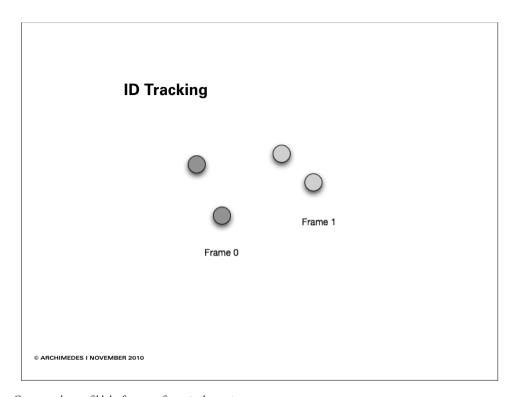
- -To find hands above the surface, simply run the standard algo w/o highpass
- -Touches can be correlated to hands: fingers are inside of hands

# **DI Tracking: Hover**

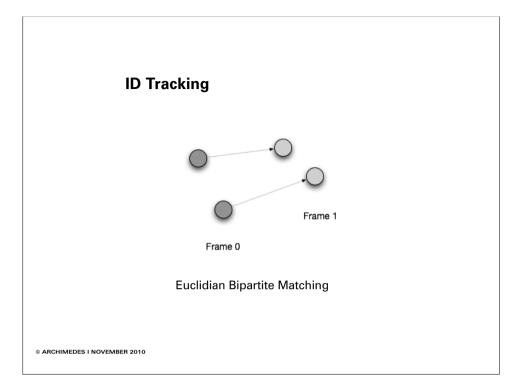




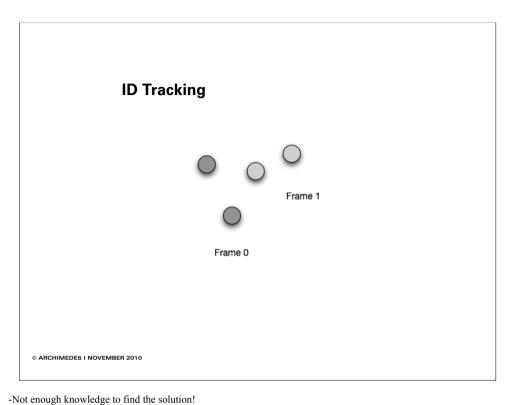
- -PCA: Principal Components Analysis.
- -Delivers an ellipse that approximates the blob.
- -Center of the blob is average of all pixel coordinates of the blob
- -First ellipse axis is the axis with the greatest variance
- -Can be derived analytically, involves covariance matrix, eigenvalues etc. and can be found in any good statistics book
- -Why? -> Object classification, Hand direction,...



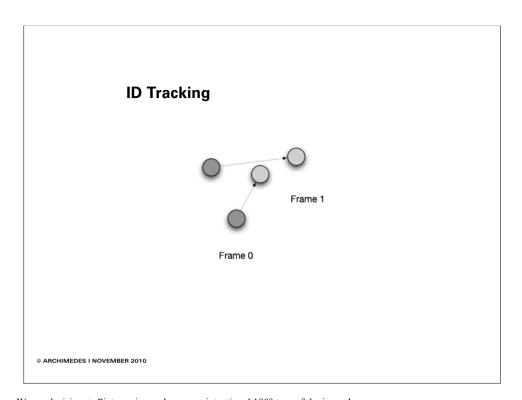
- -Correspondence of blobs from one frame to the next.
- -Theoretical solution: Euclidian Bipartite Matching



- -Naive algorithm runs in O(n3) or so...
- -Lots of papers on optimization, but
- -They miss the real problem







-Wrong decision -> Picture viewer does an unintentional 180° turn of the image!



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# **ID Tracking: Dead Reconing**

[Ridley, Mark, 1613. "A short treatise of magneticall bodies and motions"]

#### CHAP. XXXXII.

# Of finding the variation of the Inclinatory-needle.

Auing declared the manifold causes of Auing declared the manifold causes of the variation of the Inclinatory-needle from his true and naturall angle of incli-nation with the horizon; it followeth that we deliuer plainely how to difcerne these euents when they shall fall out, which are known perfectly by having the true elevation of the pole. where these matters shall be required.

The rules and wayes how to know the eleuation of the pole in all places, is so perfectly set out by most Astronomers and writers of Nauigation, and so well knowne to all expert Pilots, that it is a thing needleffe

here to repeate them.

Besides the ingenious Pilot knowing the eleuation of the pole in some places of his voyage that he hath paffed, by keeping a true, not a dead reckoning of his course in pricking his Card aright, and obseruing the way with the logge-line, with other currants and occurrants, will give a very artificiall conjecture of the elevation of the pole in that place where he is, though he fee neither Sunne nor Starres.

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V 2 Notwith-

#### CHAP. XXXXII.

# Of finding the variation of the Inclinatory-needle.

Auing declared the manifold causes of the variation of the Inclinatory-needle from his true and naturall angle of inclination with the horizon; it followeth that we deliuer plainely how to different these euents when they shall fall out, which are known

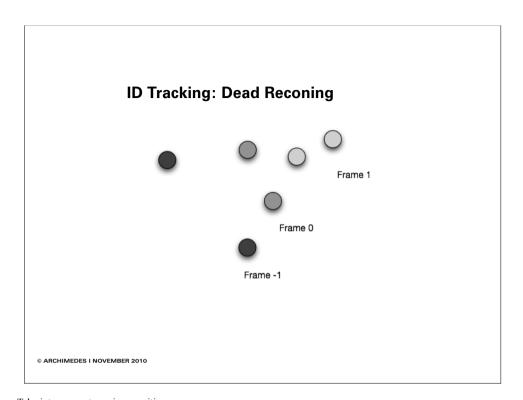
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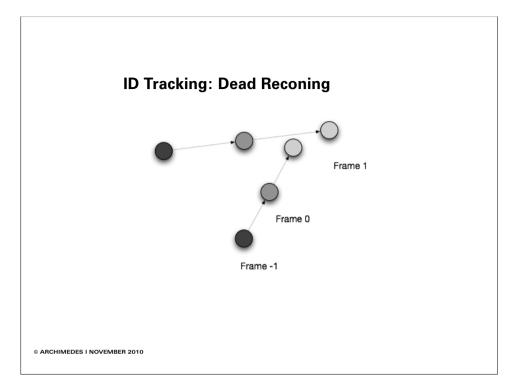
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Besides the ingenious Pilot knowing the elevation of the pole in some places of his voyage that he hath paffed, by keeping a true, not a dead reckoning of his courfe in pricking his Card aright, and obseruing the way with the logge-line, with other currants and occurrants, will give a very artificiall coniecture of the elevation of the pole in that place where he is, though he fee neither Sunne nor Starres.

Notwith-



- -Take into account previous positions
- -Determine where the finger should be
- -Take that as basis for the matching algorithm



- -Take into account previous positions
- -Determine where the finger should be
- -Take that as basis for the matching algorithm

# **ID Tracking: Simple Matching Algorithm**

Calculate all blob distances, put into heap structure While heap not empty:

Match blobs with the shortest distance

Easy optimization: Ignore everything over a maximum distance.

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- -With dead reconing, a simplified approximate matching algorithm works
- -Fingers have a maximum distance they can travel in a frame

# **Object Tracking**

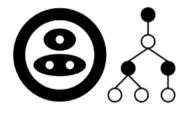
· Markerless: Use Values from PCA

• Marker-based: E.g. fiducials

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-If the objects have different forms: use values from PCA to categorize them

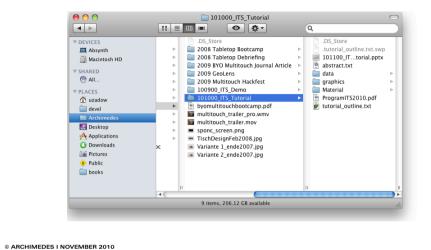
# **Object Tracking: Fiducials**



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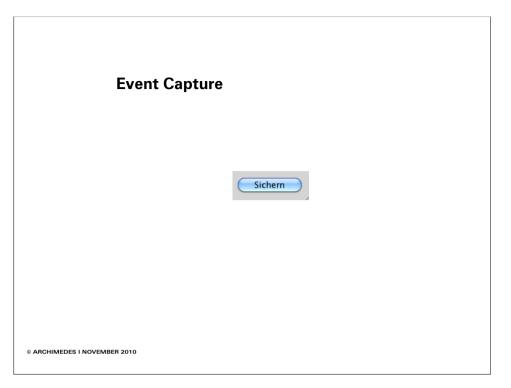
- -Blob tracking gives tree of blobs.
- -The tree topology is used as unique ID.

# **Event Bubbling**

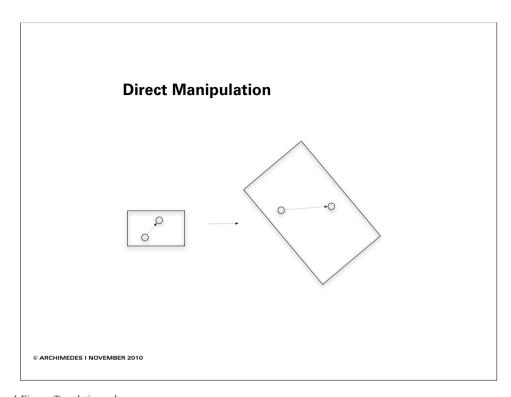




- -Time-honored interface: UI elements form a hierarchy
  - In this case: button->scrollbar->window
- -Events travel up the hierarchy
  - Button can have event handler, then scrollbar, etc.
- -Old, but stays useful for MT.



- -Show os window close button
- -Event capture: Applications can request that events from a contact be sent to a specific UI element, even if the contact leaves the element.



-1 Finger: Translation only

-2 Fingers: Simple 2D affine transform

->2 Fingers: hm.

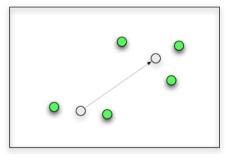
# 

# **Direct Manipulation: k-means**

```
p1, p2 = two of the touch points
repeat
  group points by distance to p1 or p2
  p1, p2 = centers of groups
until p1, p2 stops changing
```

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# **Direct Manipulation: k-means**



# **Direct Manipulation: k-means**

When fingers appear/disappear:

calc k-means with new positions of old fingers move object accordingly calc new basis for transforms w/o moving

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-Result: If no finger moves but a new one appears, the object doesn't move.

# **Direct Manipulation: Inertia**

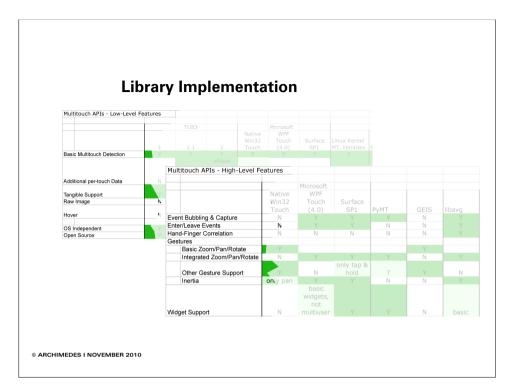
Extremely simple 'Physics':

- · Calculate current speed on up event
- Decelerate

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-To determine the initial speed, average several frames to reduce jitter

# Library Implementation Done :-)



-This is one way to implement things – there are lots of alternatives

-

<sup>-</sup>To determine the initial speed, average several frames to reduce jitter

# **APPLICATION-LEVEL CONSIDERATIONS**

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- -Archimedes builds science museums.
- -Interesting experiences with multitouch 'in the wild'

# **MUSEUM SETTING**

A science museum is a place to learn things:

- Content must be scientifically sound
- Communication with scientists

- Scientifically verifiable content
- Scientific communication: precise, verbose, peer audience (other scientists)

# **MUSEUM SETTING**

#### Example: Scientific communication

[Tsai 87] R. Tsai. "A Versatile Camera Calibration Technique for High-Accuracy 3D Machine Vision Metrology Using Off-The-Shelf TV Cameras and Lenses." IEEE Journal of Robotics and Automation 3:4 (1987), 323–344.



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- Scientifically verifiable content
- Scientific communication: precise, verbose, peer audience (other scientists)

# **MUSEUM SETTING**

People don't stay forever:

- 2-3 hours per exhibition
- 2-5 minutes per exhibit!

- Scientists often aren't trained to explain to a layman.
- Is it *possible* to explain the paper on the last slide in 2-5 minutes?
- Tendency to cram too much data into exhibits

# **COPING WITH SHORT DWELL TIMES**

- Very short learning phase, so:
   Self-evident interaction techniques
- Interaction often on a visceral, intuitive, emotional level
- Long text is almost always out of place

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-Problem: Self-evident but still novel, attention-grabbing, etc...

# INTERACTION DESIGN FOR MUSEUMS

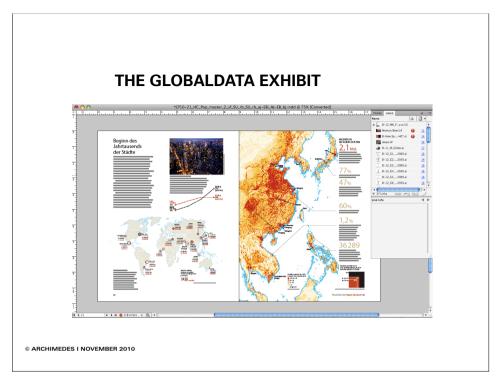
Example workflow: GlobalData exhibit in the Science Express Germany

Initial constraints:

- Use Session Desk
- Use data from National Geographics (2008 special issue on Planet Earth)

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- Demo tomorrow evening



So we had 50 pages of indesign documents from this NG issue.



Initial application sketch – a short movie showing the interaction

This was for a repeat customer, so there was a lot of trust and we basically got a 'go' at this point.

Found additional data: Per-country data on World population 1950-2050.



Show live application.

# THE GLOBALDATA EXHIBIT

# Study in the train:

- Collaboration with Johannes Schöning, Florian Daibler and Antonio Krüger, Saar University
- Observed interactions with this exhibit for a day

#### THE GLOBALDATA EXHIBIT

#### Visitors:

- Wide age span of visitors
- Group sizes 1-5 + some school classes

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Show live application.

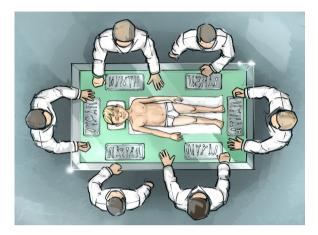
#### THE GLOBALDATA EXHIBIT

#### Interaction:

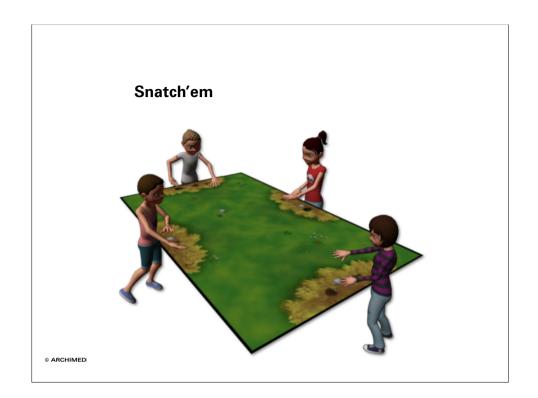
- Interaction time 5 secs to 10 mins, mean 3 mins
- · Lots of collaboration
- 1/3 didn't realize the exhibit was interactive
- 1/3 used only one finger
- Of the ones using one finger: 50% didn't use drag
- No differences due to age
- But: Most users interacted with actual content

- As soon as one visitor started interacting, others joined
- One finger: handbags/coats!
- Age: Younger visitors->more experimentation, older ones -> more observation
- Short explorative period, presses on non-interactive elements etc., then longer interaction with the actual content

# SimMed



- As soon as one visitor started interacting, others joined
- One finger: handbags/coats!
- Age: Younger visitors->more experimentation, older ones -> more observation
- Short explorative period, presses on non-interactive elements etc., then longer interaction with the actual content





Personal space issues!

